



Lymph Node Gross Tumor Volume Detection and Segmentation via Distance-based Gating using 3D CT/PET Imaging in Radiotherapy









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Background

LN in Oncology

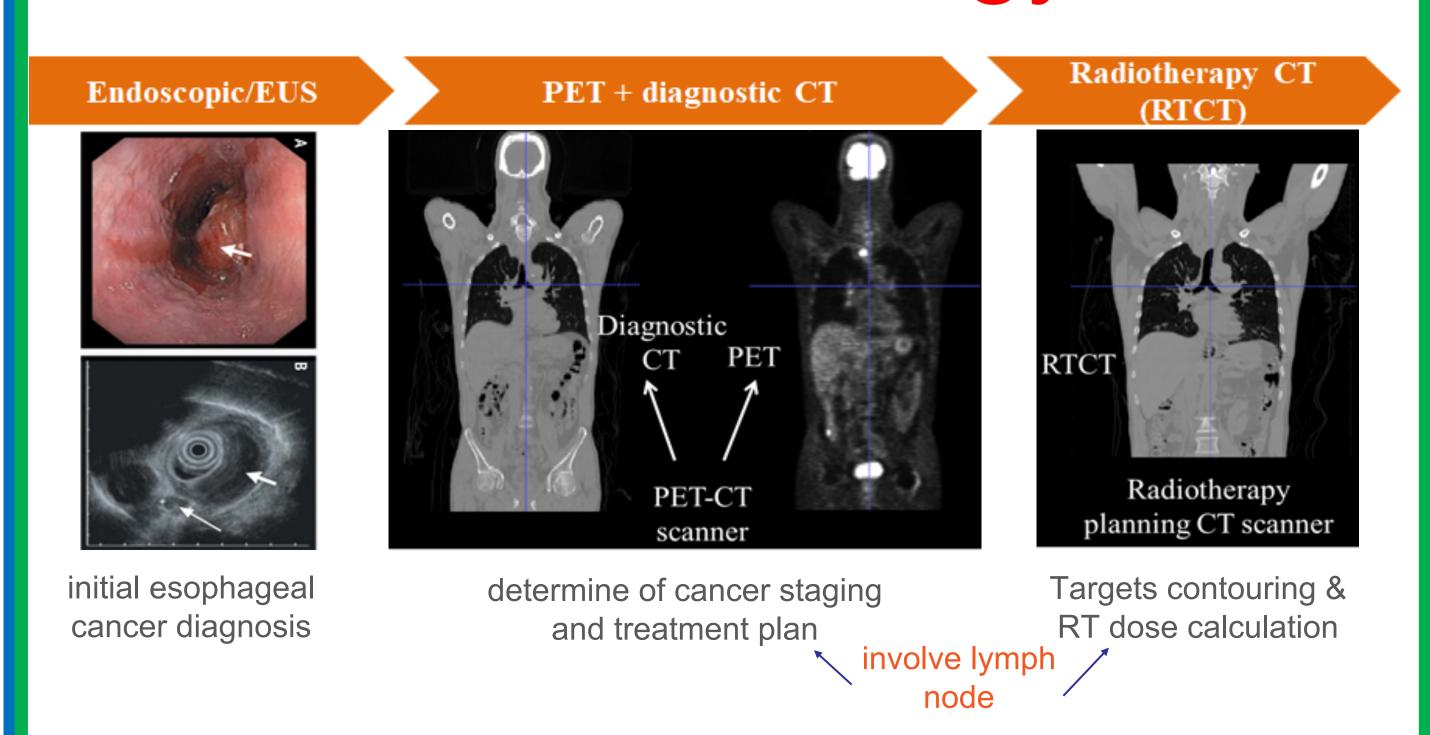


Figure 1. The workflow of esophagus cancer treatment, in which the second and third steps are involved with the lymph nodes.

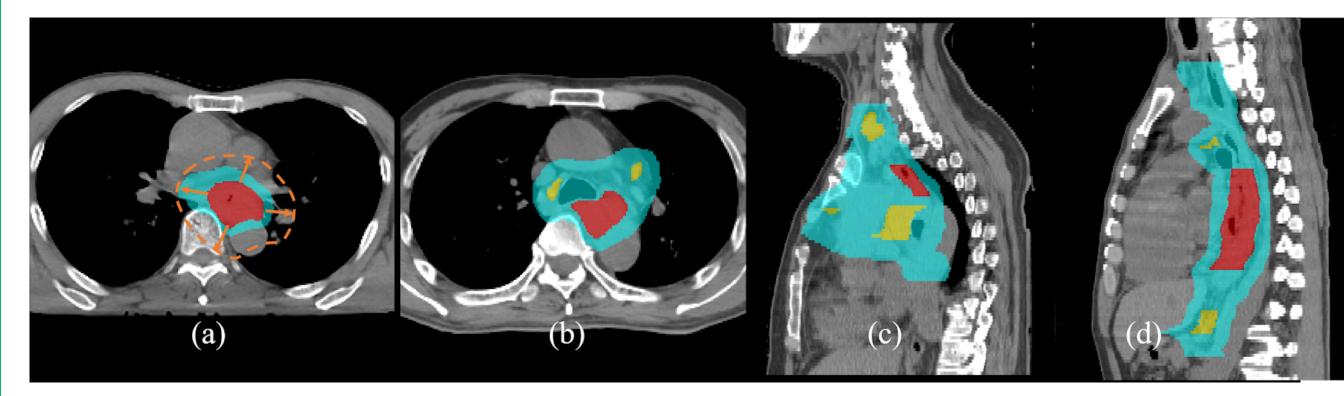


Figure 2. In radiotherapy, the radiation covers the primary tumor and lymph node gross tumor volume (GTV_LN).

Challenges

We are the first to address the clinically critical task of detecting, identifying and characterizing GTV LNs.

- Size and shape is in a large variance
- Radiotherapy is on the non-contrast CT (RTCT)
- GTV LNs have more distributions in smaller sizes than enlarged LNs

In order to do this, we collected 141 patients with esophageal cancer (underwent radiotherapy treatment), in average 4 ~ 5 GTV_LNs for each patient, 651 GTV_LNs in total, all of them are on non-contrast CT with the labelled GTV LN volume mask.

Proposed Method

Dataset

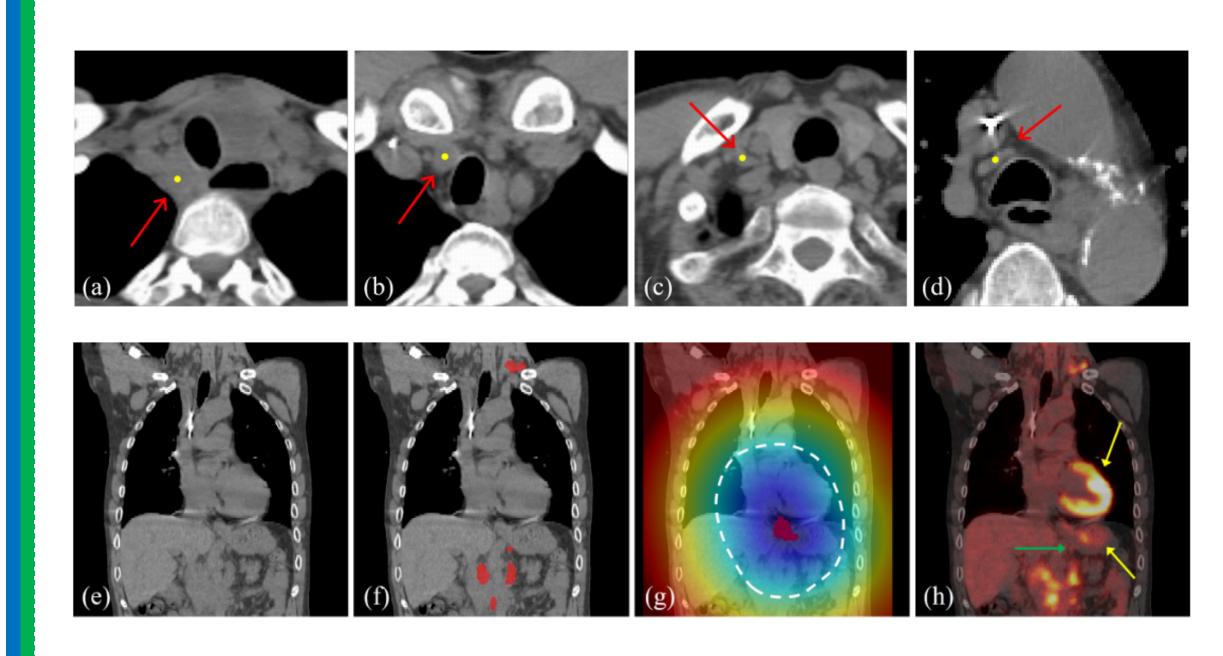


Figure 3. Top row (a-d): examples of the GTV_LN (red arrow) with varying size and appearance at scatteredly distributed locations. Bottom row (e-h): (e) A coronal view of RTCT for an esophageal cancer patient. (f) The manual annotated GTV_LN mask. (g) The tumor distance transformation map overlaid on RTCT, where the primary tumor is indicated by red in the center and the white dash line shows an example of the binary tumor proximal and distal region division. (h) PET imaging shows several FPs with high signals (yellow arrows). Two FN GTV_LN are indicated by green arrow where PET has even no signals on a GTV_LN .

Framework

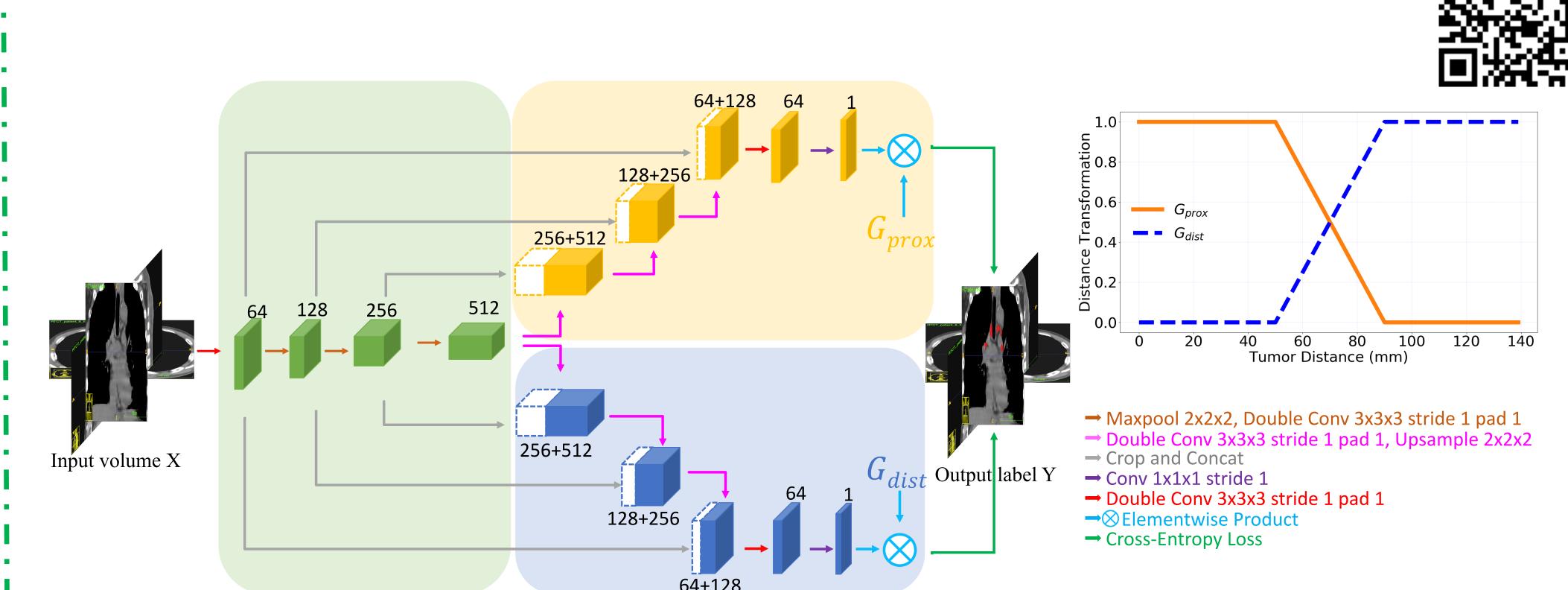


Figure 4. The overall framework of our proposed multi-branch GTV_LN detection and segmentation method. The light green part shows the encoder path, while the light yellow and light blue parts show the two decoders, respectively. The number of channels is denoted either on the top or the bottom of the box.

Results

Table 1. Quantitative results of our proposed methods with the comparison to other setups and the previous state-of-the-art.

Methods	single-net		multi-net BG[21]	multi- branch BG (Ours)	multi- branch SG (Ours)	MULAN [17]	
СТ	\checkmark					✓	
EF		✓	✓	✓	✓		✓
mRecall	0.66	0.73	0.75	0.76	0.78	0.71	0.73
Recall max	0.76	0.82	0.83	0.85	0.84	0.76	0.78
mRFOC	0.60	0.68	0.70	0.68	0.72	0.63	0.71
FROC @4	0.55	0.67	0.67	0.67	0.73	0.63	0.72
FROC @6	0.68	0.71	0.74	0.72	0.74	0.64	0.72

Multi-net (EF) Multi-branch SG (EF) RTCT / GTV LN MULAN (CT)

Figure 5. Four qualitative examples of the detection results using different methods. Red color represents the ground-truth GTV_LN overlaid on the RTCT images; Green color indicates the predicted segmentation masks.